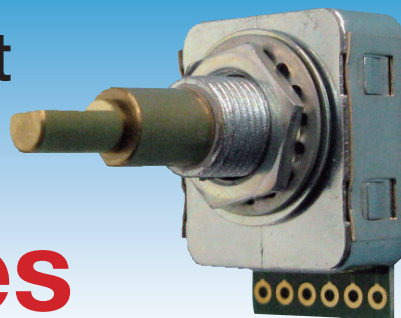


Rotary Encoder with Dual Functional Shaft



RE24 Series



Outline

RE24 rotary encoder series contain unique mechanism for its shaft; its rotational outer axis for rotary encoder and the inner axis for push switch. RE24 is designed for use in various industrial areas: measurement component, medical equipment, industrial machinery, telecommunication device and machine tool.

Features

- Dual inner/outer axes mechanism to help prevent misoperation
- Eco friendly:
 - 1) Low cost and lesser parts by VA design
 - 2) RoHS compliant
- Thin-line (18.8x25.5x8.9mm) and lightweight (18g)
- Long-lasting without “contact chatter” due to its optical switching function
- Specially designed knob (GG60) available

Specifications

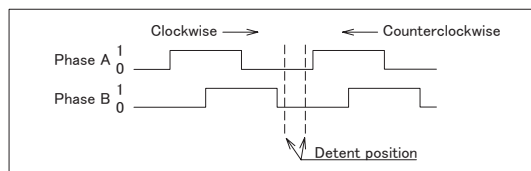
1. Electrical and Mechanical specifications			
Items		Rated Value	
Number of pulses		16PPR, 25PPR	
Supply voltage		3.3V±10%	5V±10%
		20mA	10mA
Output signals		two square wave output (A/B), CMOS chip	
Output voltage	High	(Supply Voltage - 0.5V) ≤	
	Low	≤ 0.5V	
Response frequency		200Hz	
Rotational torque	Light: S	4±1mN · m	
	Standard: C	6±2mN · m	
	Medium: M	10.5±3.5mN · m	
	High: H	16±5mN · m	
Push switch	Rating of contact	≤ DC12V	0.1 ~ 10mA
	Travel of switch	0.2±0.1mm	
	Operational Force	S	3.2±1N
		M	4.0±1N
		H	5.0±1N
Weight		18g	

Note : In case Rotational Torque M or H, Operational Torque should be either M or H.

2. Reliability and Environmental specifications			
Items			Rated Value
Durability of operating area	Thrust direction	Push	100N
		Pull	50N
	Radial		1N · m
Rotational durability	Light: S	1 million strokes (No load)	
	Standard: C		
	Medium: M		
	High: H	100 thousand strokes (No load)	
Screw Torque			Not more than 1N · m
Heat resistance of solder	Solder bit temp.: MAX 350℃	Within 3 seconds for each terminal	
Operating temperature			0℃ ~ +55℃ 32F ~ 131F
Storage temperature			- 40℃ ~ +85℃ - 40F ~ 185F

Output Waveform

- 1) Turning the shaft clockwise will generate the signal A when the signal B outputs a low voltage (0);
- 2) Rotating the shaft counter-clockwise will generate the signal A when the signal B outputs a high voltage (1);
- 3) Detent positions are where both signal A and B are low (0).

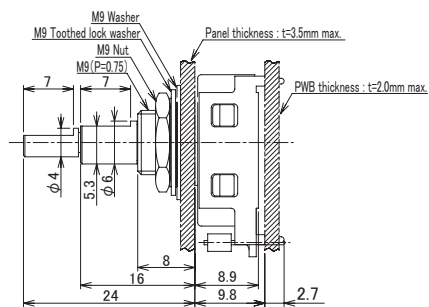
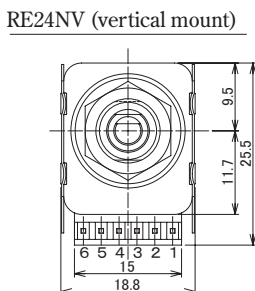
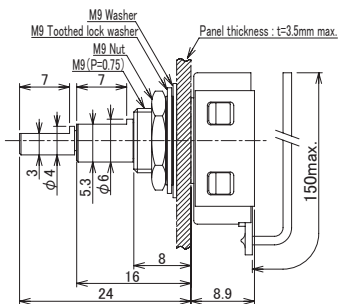
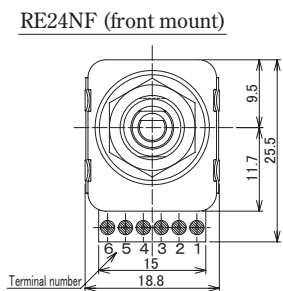
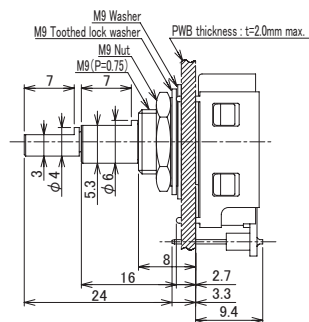
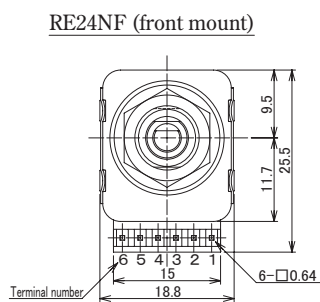
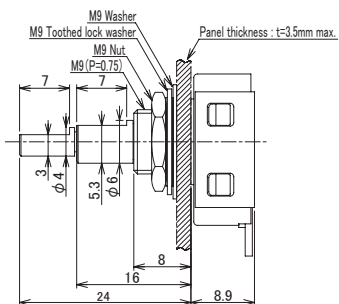
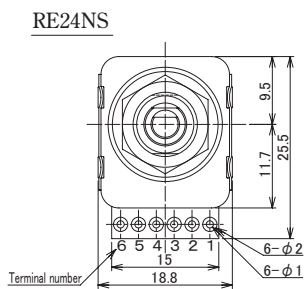


Part Number Designation

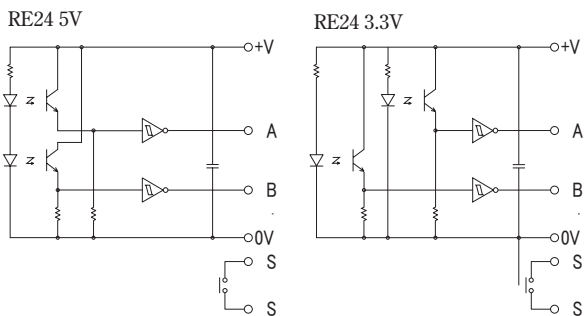
Diagram illustrating the connection of the motor's pins to the breadboard:

- RE24**: Connected to **Series**.
- N**: Connected to **Waterproof** (No).
- S**: Connected to **Pulse** (16PPR, 25PPR).
- 25**: Connected to **Push Switch Force** (S 3.2N, H 5N).
- C**: Connected to **Rotation Torque** (S 4mN · m, C 6mN · m, M 10.5mN · m, H 16mN · m, Non W/O $\leq 4\text{mN} \cdot \text{m}$).
- 16/24**: Connected to **Shaft length** (16 16mm (inner), 20 24mm (outer)).
- R**: Connected to **Shaft Shape** (F Flat).
- A**: Connected to **Power Voltage** (A 5V, B 3.3V).

Dimensions (mm)



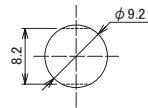
Circuitry



Terminal number

1	3.3V/5V	Supply
2	A	Signal A
3	B	Signal B
4	0V	Ground
5	S	Push Switch
6	S	Push Switch

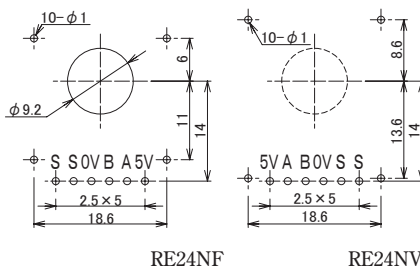
Mounting hole dimensions (mm)



Precautions

Wiring	Use buffering amplifier when extending lead wire over 30cm.
Soldering	Do not put a load on the terminal area during and immediately after soldering.
Operation	Do not use flow/reflow soldering machines.
Power	Use under specified power voltage and connect properly.
Waterproofing	Do not fasten tighter with the torque of more than 1.5N·m.

PWB mounting hole dimensions (mm)



Warranty

- 1 year from the date of shipment.